

06/07: Embedded architectures & MCU datasheets





Review

- ◆ Sensors and actuators (I/O devices) can be analog or digital
- ◆ MCUs can read from/write to I/O devices
 - ◇ GPIO pins (for digital signals and PWM)
 - ◇ DACs, ADCs (for analog signals)
 - ◇ This enables us to use software to interact with the physical world



General purpose computing and I/O

When you run code on a computer:

- ◆ How is the program able to read input (user/keyboard input or files)?
- ◆ How is the program able to create output (write to files/draw pixels on a screen)?

Operating system provides interfaces that translate commands into appropriate hardware actions



MCUs are varied

[Wikipedia list](#)

Variations in:

- Word size
- Memory
- I/O and peripherals

Without an OS, it is the programmer's role to understand the specifics of the MCU hardware



Architecture

The organization and design of a computer

Defines the SW/HW interface

- ◆ Instruction Set Architecture (ISA): *machine code, word sizes, memory addresses, data formats, registers*
- ◆ Microarchitecture (implementation of ISA): CPU internals, memory hierarchy
- ◆ Systems design: all other HW support



How software you write becomes code running on an CPU

Code you write



Assembly Code



Machine code



Program

```
int N = 12;
int fibo = 0;

void setup() {
  int f_prev = 1;
  int f = 1;

  int i = 0;

  while (i < N) {
    int f_next = f + f_prev;
    f_prev = f;
    f = f_next;
    i += 1;
  }
  fibo = f;
}

void loop() {
  Serial.println(fibo);
  delay(100);
}
```

Assembly

Memory address of instruction

```
000020fc <setup>:
 20fc: 4b07
 20fe: b510
 2100: 681c
 2102: 2301
 2104: 2200
 2106: 0019
 2108: 4294
 210a: dd04
 210c: 18c8
 210e: 3201
 2110: 0019
 2112: 0003
 2114: e7f8
 2116: 4a02
 2118: 6013
 211a: bd10
 211c: 20000000
 2120: 200000bc

00002124 <loop>:
 2124: b510
 2126: 4b05
 2128: 220a
 212a: 6819
 212c: 4804
 212e: f002 f8d6
 2132: 2064
 2134: f000 f8c2
 2138: bd10
 213a: 46c0
 213c: 200000bc
 2140: 200001a4
```

Instruction in machine code (hex)

```
ldr r3, [pc, #28] ; (211c <setup+0x20>)
push {r4, lr}
ldr r4, [r3, #0]
movs r3, #1
movs r2, #0
movs r1, r3
cmp r4, r2
ble.n 2116 <setup+0x1a>
adds r0, r1, r3
adds r2, #1
movs r1, r3
movs r3, r0
b.n 2108 <setup+0xc>
ldr r2, [pc, #8] ; (2120 <setup+0x24>)
str r3, [r2, #0]
pop {r4, pc}
.word 0x20000000
.word 0x200000bc

ldr r3, [pc, #20] ; (213c <loop+0x18>)
movs r2, #10
ldr r1, [r3, #0]
ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
bl 42de <_ZN7arduino5Print7printlnEii>
movs r0, #100 ; 0x64
bl 22bc <delay>
pop {r4, pc}
nop ; (mov r8, r8)
.word 0x200000bc
.word 0x200001a4
```

Assembly instructions

Types of data

```
ldr r3, [pc, #28] ; (211c <setup+0x20>)
push {r4, lr}
ldr r4, [r3, #0]
movs r3, #1
movs r2, #0
movs r1, r3
cmp r4, r2
ble.n 2116 <setup+0x1a>
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str r3, [r2, #0]
pop {r4, pc}
```

registers

immediates

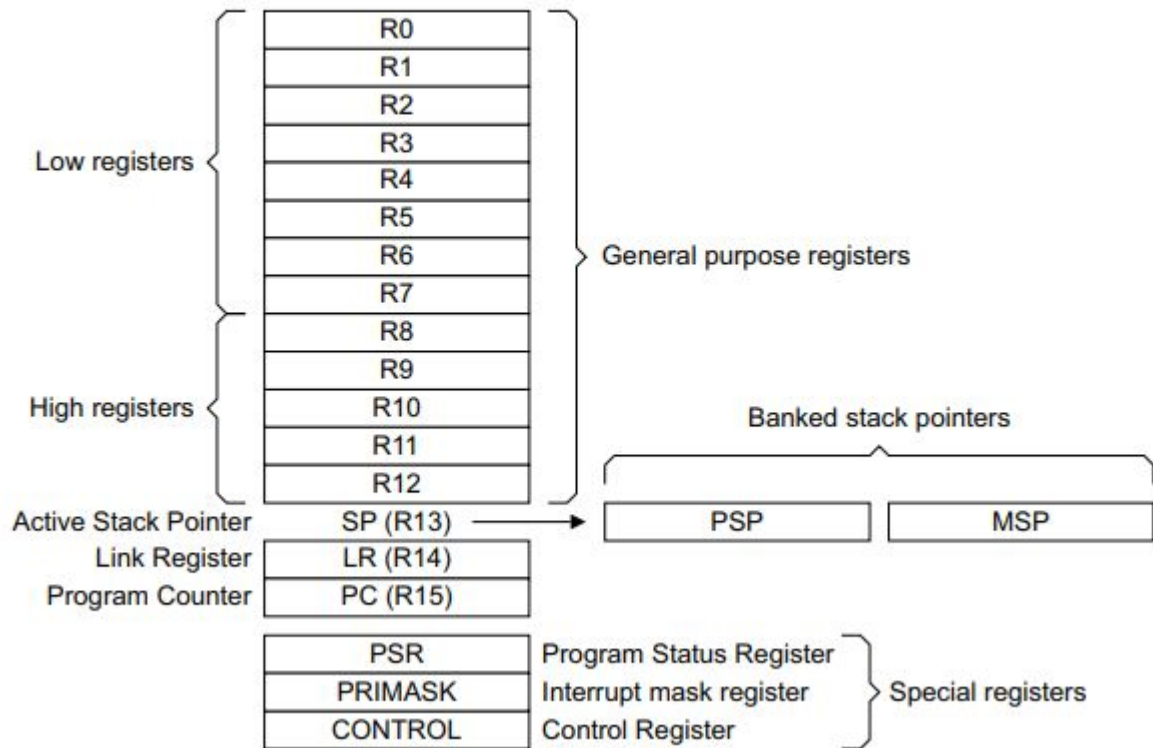
memory addresses
(raw or computed from
registers/immediates)



Registers

- ◆ Small pieces of fast memory
- ◆ Usually 8-, 16-, 32- or 64-bits
- ◆ Many purposes on CPUs and MCUs:
 - ◇ Storing temporary data for execution
 - ◇ Addressing memory
 - ◇ Configuring peripherals (Lab 3)

The processor core registers are:



Types of operations

```
ldr r3, [pc, #28] ; (211c <setup+0x20>)  
push {r4, lr}  
ldr r4, [r3, #0] ; register operations  
movs r3, #1  
movs r2, #0 ; stack operations  
movs r1, r3  
cmp r4, r2  
ble.n 2116 <setup+0x1a>  
adds r0, r1, r3 ; memory loads/stores  
adds r2, #1  
movs r1, r3  
movs r3, r0 ; control logic  
b.n 2108 <setup+0xc>  
ldr r2, [pc, #8] ; (2120 <setup+0x24>)  
str r3, [r2, #0]  
pop {r4, pc}
```

Stack

LIFO (last-in, first-out) data structure

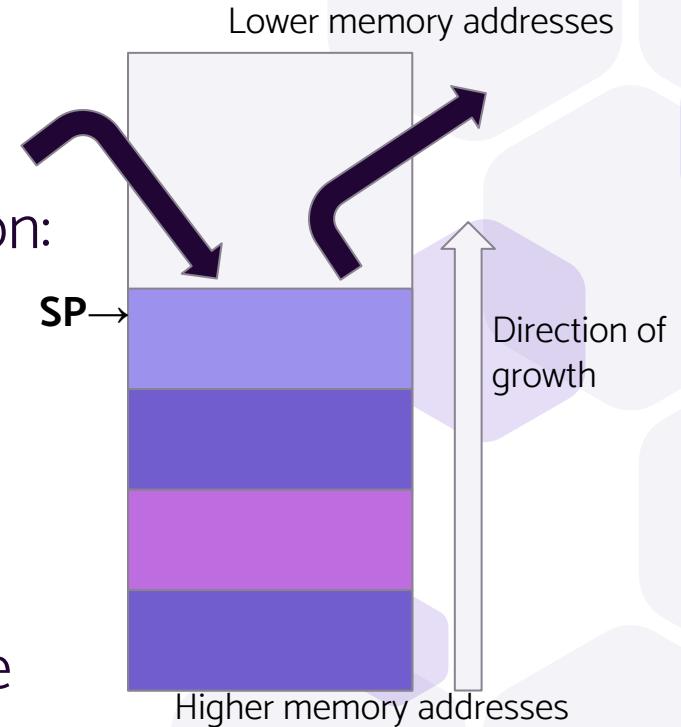
Keeps track of information for execution:

- Local variables

- Return pointers

Grows “downward”

Stack Pointer (SP) points to latest value





What a processor needs to do:

Fetch an instruction from memory

Decode the instruction

Execute arithmetic and logical operations

Load/store values in **Memory**

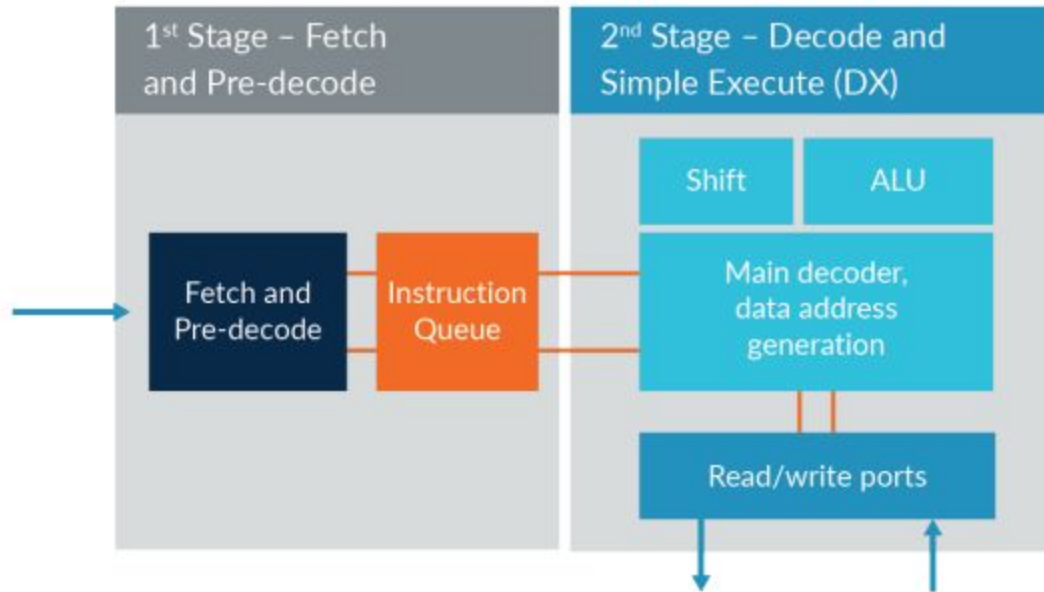
Write back values to registers

Different CPUs do these in different orders/groupings
and in different ways



Cortex-M0+

Cortex-M0+ Pipeline





Memory

Information stored in memory:

Code

Program data

Stack

Heap (dynamically allocated data)

Register file

Every location in memory has an **address**

```
Disassembly of section .data:
```

```
20000000 <N>:
```

```
20000000:      0000000c
```




Types of memory

Volatile - Gets erased when power gets turned off

RAM (DRAM, SRAM)

Non-volatile - Persists when power gets turned off

Flash

ROM (sometimes rewritable, like EEPROM)



Specifications

x-bit processor:

Data registers, data buses, *words* are that size

memory address may not be that size

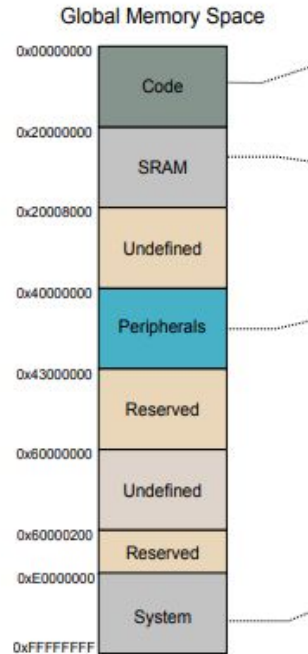
Common for 8-bit CPUs to have 16-bit addresses (**why?**)

What are the implications for atomicity?

Harvard Architecture - code has separate memory space from data
(common in MCUs)

vs. Von Neumann - shared memory space (SAM D21 is Von Neumann)

Memory layout of SAMD 21 chip





How information gets onto an MCU

Bootloader

Firmware on the board that can interface with the computer

Copies memory on upload

Hardware programmer

Special piece of hardware that connects to pins directly and transfers using a protocol



Peripherals

Timers, ADCs, GPIO, etc

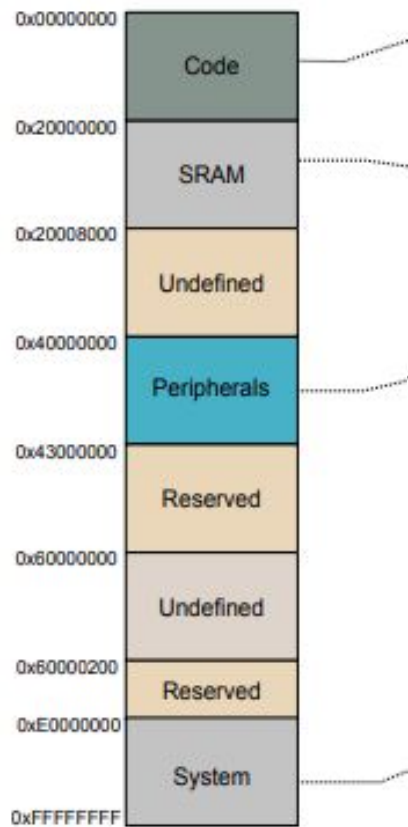
Controlled by special registers (**different** from CPU registers!)

You will see this in lab!

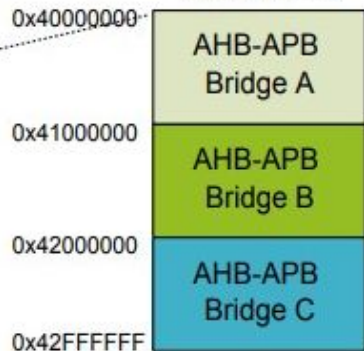
“Memory-mapped”: from CPU perspective, just like writing to any other memory address

From MCU perspective, need controller hardware to configure/send data to the right place

Global Memory Space



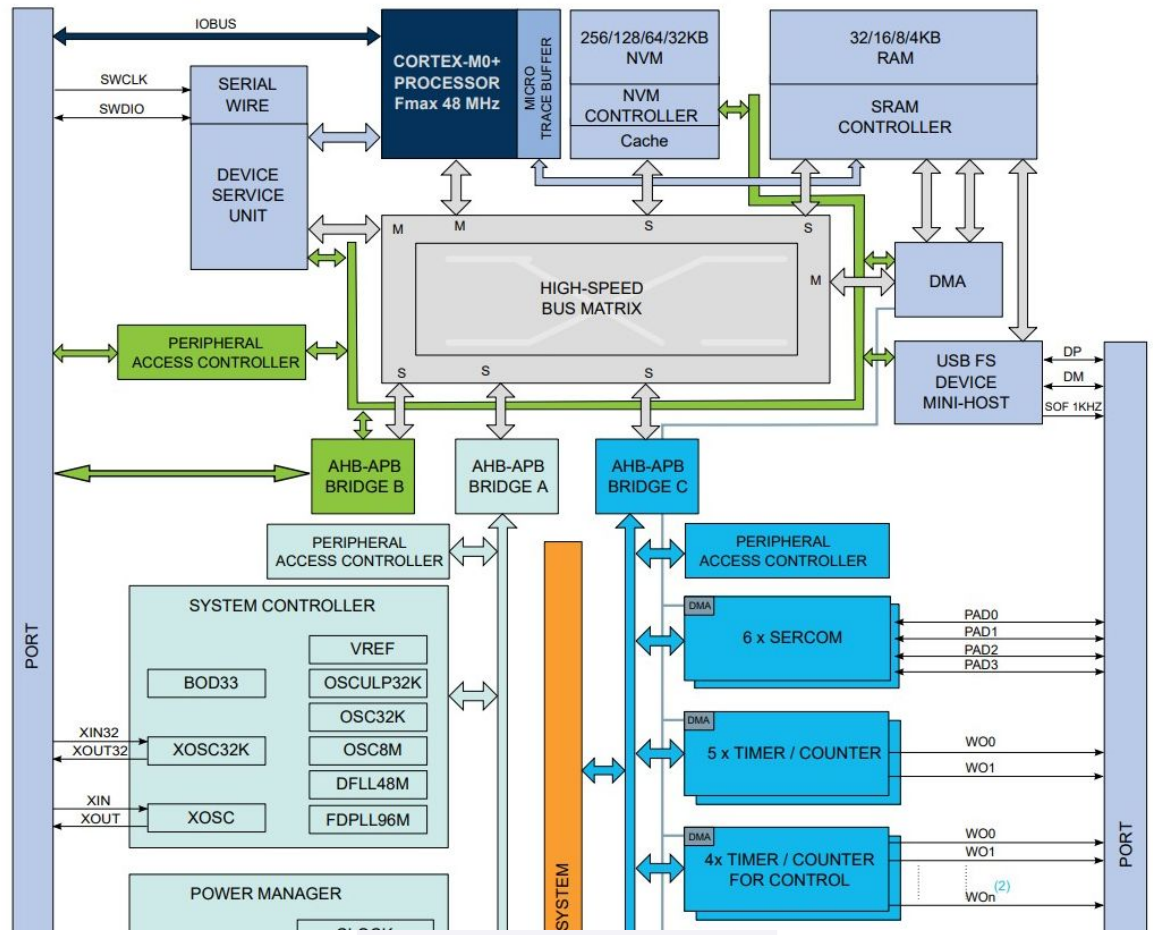
AHB-APB



AHB-APB Bridge B

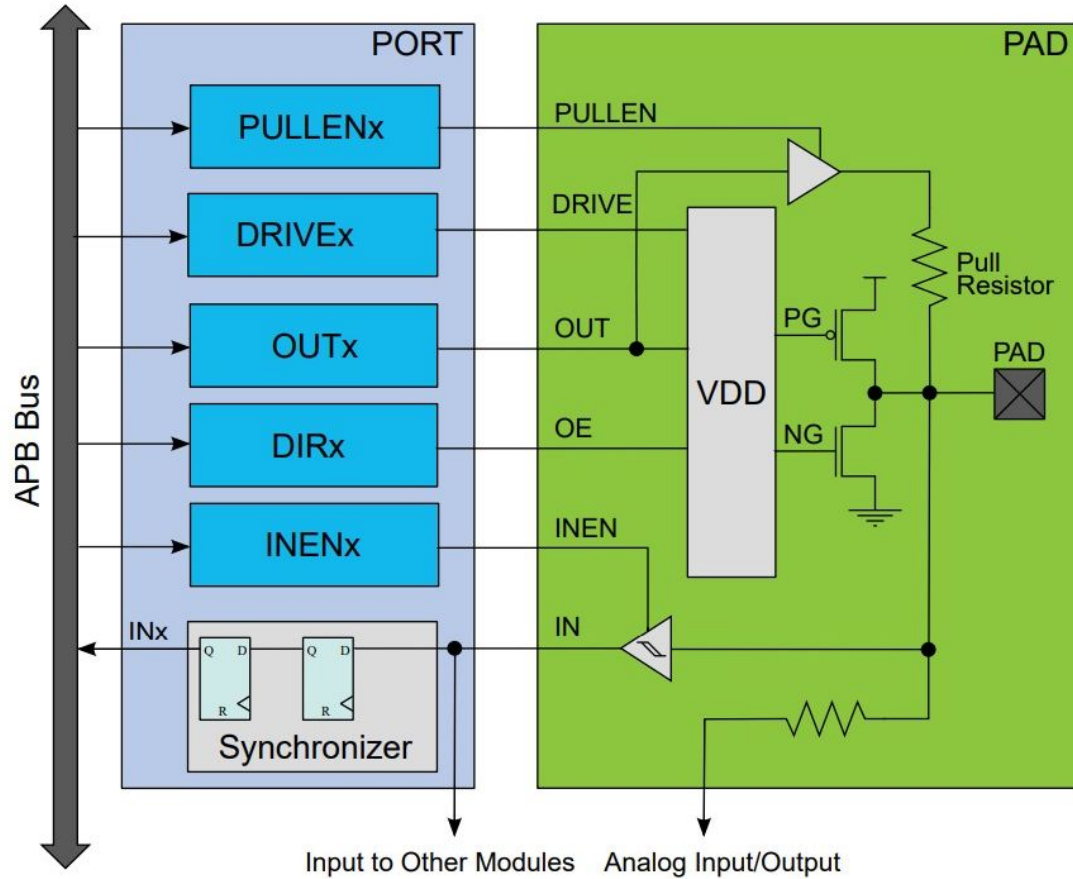


4. Block Diagram



23.6 Functional Description

Figure 23-2. Overview of the PORT





MCU datasheet example

Configure and write to DAC



Resources used in this presentation

[ARM Cortex M0+ devices generic user guide](#)

[ARMv6-M Architecture reference manual](#)



Supplement: execution of assembly

A2.3.1 ARM core registers

There are thirteen general-purpose 32-bit registers, R0-R12, and an additional three 32-bit registers that have special names and usage models:

SP Stack Pointer, used a pointer to the active stack. For usage restrictions see *Use of 0b1101 as a register specifier* on page A5-83. This is preset to the top of the Main stack on reset. See *The SP registers* on page B1-211 for more information. SP is sometimes referred to as R13.

LR Link Register stores the Return Link. This is a value that relates to the return address from a subroutine that is entered using a Branch with Link instruction. The LR register is also updated on exception entry, see *Exception entry behavior* on page B1-224. LR is sometimes referred to as R14.

———— **Note** —————

LR can be used for other purposes when it is not required to support a return from a subroutine.

—————

PC Program Counter, see *Use of 0b1111 as a register specifier* on page A5-82 for more information. The PC is loaded with the Reset handler start address on reset. PC is sometimes referred to as R15.



Cortex M0+ stack operations

push *reglist* - push the registers in *reglist* onto the stack (highest value registers pushed first), decrements stack pointer

pop *reglist* - pop the values on the stack into the registers in *reglist* (lowest value registers popped first)

if SP is in *reglist*, branch to where SP is pointing after pop



Loads and stores

An instruction like `ldr r1 [r2, #8]` means:

- ◆ Add 8 to the value in register `r2`
- ◆ Interpret the result as a memory address
- ◆ Take the value stored at that memory address and put it in `r1`

(Similar with `str`, which is for storing values in registers to memory addresses)

mem. address $20fc + 28 = 211c$

PC

000020fc <setup>:

```
20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
20fe: b510    push {r4, lr}
2100: 681c    ldr r4, [r3, #0]
2102: 2301    movs r3, #1
2104: 2200    movs r2, #0
2106: 0019    movs r1, r3
2108: 4294    cmp r4, r2
210a: dd04    ble.n 2116 <setup+0x1a>
210c: 18c8    adds r0, r1, r3
210e: 3201    adds r2, #1
2110: 0019    movs r1, r3
2112: 0003    movs r3, r0
2114: e7f8    b.n 2108 <setup+0xc>
2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
2118: 6013    str r3, [r2, #0]
211a: bd10    pop {r4, pc}
211c: 20000000 .word 0x20000000
2120: 200000bc .word 0x200000bc
```

00002124 <loop>:

```
2124: b510    push {r4, lr}
2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
2128: 220a    movs r2, #10
212a: 6819    ldr r1, [r3, #0]
212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
2132: 2064    movs r0, #100 ; 0x64
2134: f000 f8c2 bl 22bc <delay>
2138: bd10    pop {r4, pc}
213a: 46c0    nop ; (mov r8, r8)
213c: 200000bc .word 0x200000bc
2140: 200001a4 .word 0x200001a4
```

value at that memory address

previous stack

R0	
R1	
R2	
R3	2000 0000
R4	
R5	
R6	
R7	
LR	

PC

000020fc <setup>:

```

20fc: 4b07
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2100: 681c
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2112: 0003
2114: e7f8
2116: 4a02
2118: 6013
211a: bd10
211c: 20000000
2120: 200000bc

```

```

ldr r3, [pc,
push {r4, lr}
ldr r4, [r3, #0]
movs r3, #1
movs r2, #0
movs r1, r3
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movs r3, r0
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ldr r2, [pc, #8] ; (2120 <setup+0x24>)
str r3, [r2, #0]
pop {r4, pc}
.word 0x20000000
.word 0x200000bc

```

LR (R14) pushed first because 14 > 4

00002124 <loop>:

```

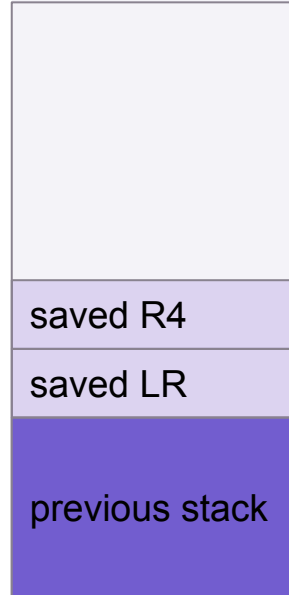
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```

```

push {r4, lr}
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nop ; (mov r8, r8)
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.word 0x200001a4

```



R0	
R1	
R2	
R3	2000 0000
R4	
R5	
R6	
R7	
LR	



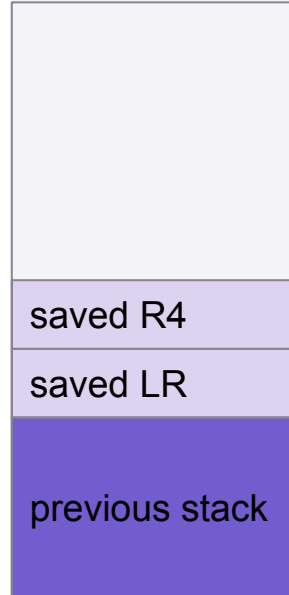
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```

mem. address 2000 0000

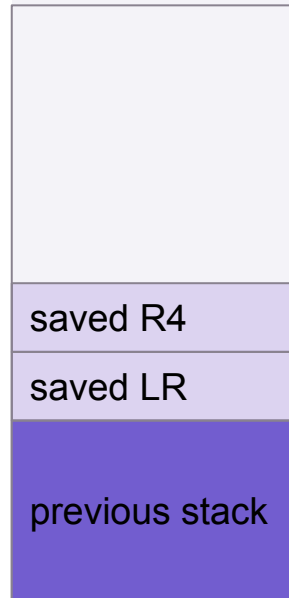


R0	
R1	
R2	
R3	2000 0000
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



```
000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
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R0	
R1	
R2	
R3	1
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	

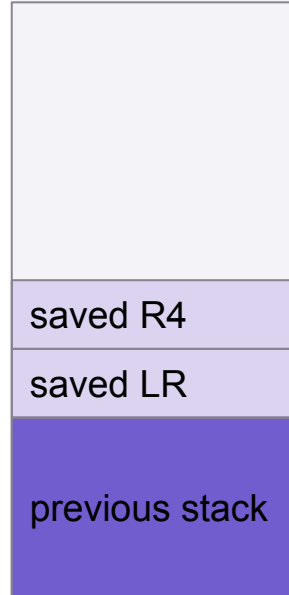


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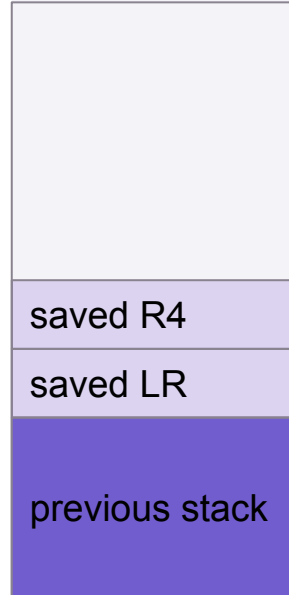


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R1	
R2	0
R3	1
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



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R1	1
R2	0
R3	1
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



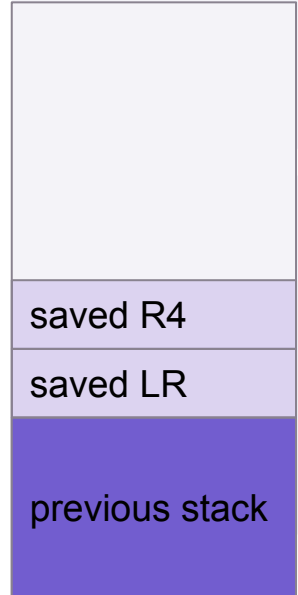
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 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```

Compute R4-R2 and set comparison flags



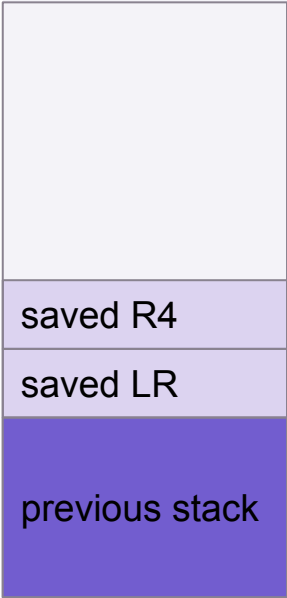
R0	
R1	1
R2	0
R3	1
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



```
000020fc <setup>:
20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
20fe: b510    push {r4, lr}
2100: 681c    ldr r4, [r3, #0]
2102: 2301    movs r3, #1
2104: 2200    movs r2, #0
2106: 0019    movs r1, r3
2108: 4294    cmp r4, r2
210a: dd04    ble.n 2116 <setup+0x1a>
210c: 18c8    adds r0, r1, r3
210e: 3201    adds r2, #1
2110: 0019    movs r1, r3
2112: 0003    movs r3, r0
2114: e7f8    b.n 2108 <setup+0xc>
2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
2118: 6013    str r3, [r2, #0]
211a: bd10    pop {r4, pc}
211c: 20000000 .word 0x20000000
2120: 200000bc .word 0x200000bc

00002124 <loop>:
2124: b510    push {r4, lr}
2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
2128: 220a    movs r2, #10
212a: 6819    ldr r1, [r3, #0]
212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
2132: 2064    movs r0, #100 ; 0x64
2134: f000 f8c2 bl 22bc <delay>
2138: bd10    pop {r4, pc}
213a: 46c0    nop ; (mov r8, r8)
213c: 200000bc .word 0x200000bc
2140: 200001a4 .word 0x200001a4
```

if r4 <= r2, jump to instruction at 2116 (otherwise, keep going)



R0	
R1	1
R2	0
R3	1
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	

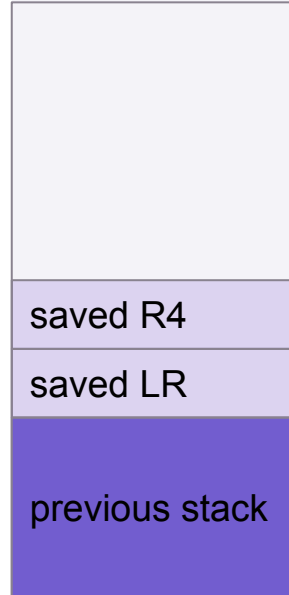


```

000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```

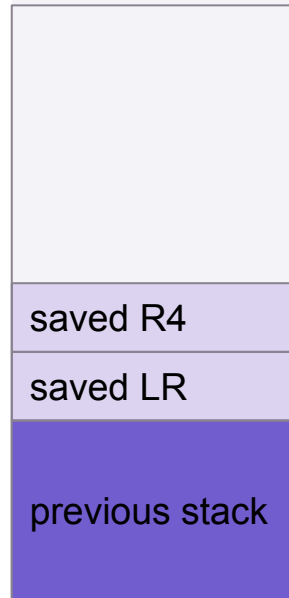


R0	2
R1	1
R2	0
R3	1
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



```
000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4
```



R0	2
R1	1
R2	1
R3	1
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	

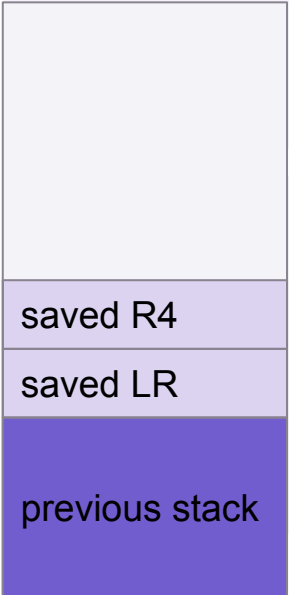


```

000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```



R0	2
R1	1
R2	1
R3	1
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	

```

000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```

PC

saved R4

saved LR

previous stack

R0	2
R1	1
R2	1
R3	2
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	

```

000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```



jump to instruction at address 2108

saved R4

saved LR

previous stack

R0	2
R1	1
R2	1
R3	2
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



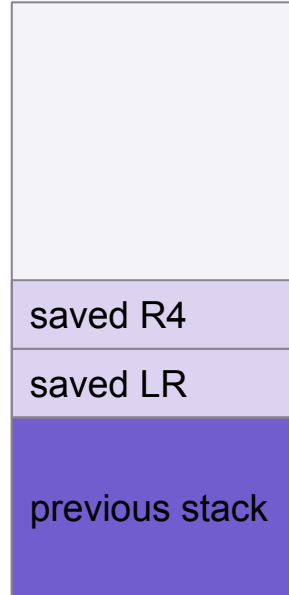
```

000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs
 2104: 2200    movs
 2106: 0019    movs
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```

Compute R4-R2 and set comparison flags



R0	2
R1	1
R2	1
R3	2
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



000020fc <setup>:

```

20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
20fe: b510    push {r4, lr}
2100: 681c    ldr r4, [r3, #0]
2102: 2301    movs r3, #1
2104: 2200    movs r2, #0
2106: 0019    movs r1, r3
2108: 4294    cmp r4, r2
210a: dd04    ble.n 2116 <setup+0x1a>
210c: 18c8    adds r0, r1, r3
210e: 3201    adds r2, #1
2110: 0019    movs r1, r3
2112: 0003    movs r3, r0
2114: e7f8    b.n 2108 <setup+0xc>
2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
2118: 6013    str r3, [r2, #0]
211a: bd10    pop {r4, pc}
211c: 20000000 .word 0x20000000
2120: 200000bc .word 0x200000bc

```

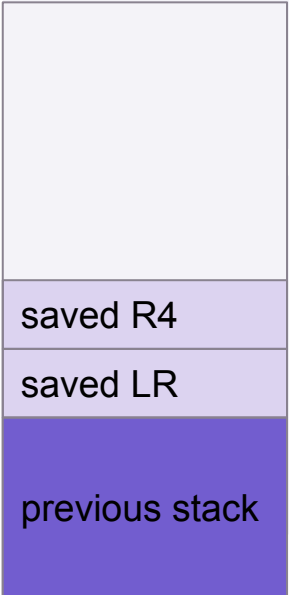
if r4 <= r2, jump to instruction at 2116 (otherwise, keep going)

00002124 <loop>:

```

2124: b510    push {r4, lr}
2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
2128: 220a    movs r2, #10
212a: 6819    ldr r1, [r3, #0]
212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
2132: 2064    movs r0, #100 ; 0x64
2134: f000 f8c2 bl 22bc <delay>
2138: bd10    pop {r4, pc}
213a: 46c0    nop ; (mov r8, r8)
213c: 200000bc .word 0x200000bc
2140: 200001a4 .word 0x200001a4

```



R0	2
R1	1
R2	1
R3	2
R4	(mem. value at 2000 0000)
R5	
R6	
R7	

LR	
----	--

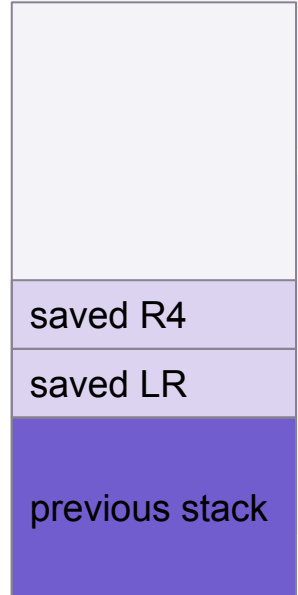


```

000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```

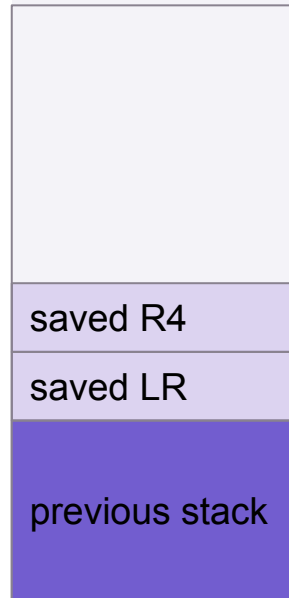


R0	3
R1	1
R2	1
R3	2
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



```
000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4
```



R0	3
R1	1
R2	2
R3	2
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	

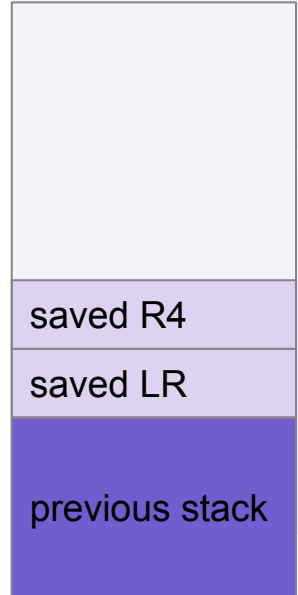


```

000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```

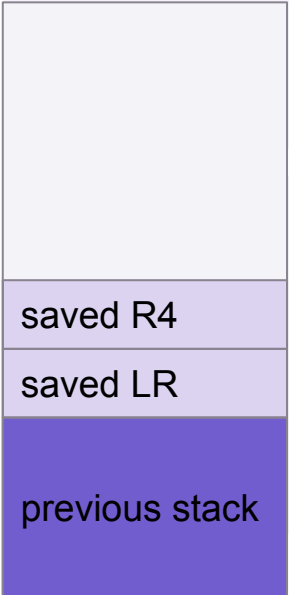


R0	3
R1	2
R2	2
R3	2
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



```
000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4
```



R0	3
R1	2
R2	2
R3	3
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	

```

000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r0
 2114: e7f8    b.n 2108 <setup+0xc>
 2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```

PC

jump to instruction at address 2108

saved R4

saved LR

previous stack

R0	3
R1	2
R2	2
R3	3
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	



```

000020fc <setup>:
20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
20fe: b510    push {r4, lr}
2100: 681c    ldr r4, [r3, #0]
2102: 2301    movs r3, #1
2104: 2200    movs r2, #0
2106: 0019    movs r1, r3
2108: 4294    cmp r4, r2
210a: dd04    ble.n 2116 <setup+0x10>
210c: 18c8    adds r0, r1, r3
210e: 3201    adds r2, #1
2110: 0019    movs r1, r3
2112: 0003    movs r3, r0
2114: e7f8    b.n 2108 <setup+0xc>
2116: 4a02    ldr r2, [pc, #8] ;
2118: 6013    str r3, [r2, #0]
211a: bd10    pop {r4, pc}
211c: 20000000 .word 0x20000000
2120: 200000bc .word 0x200000bc

00002124 <loop>:
2124: b510    push {r4, lr}
2126: 4b05    ldr r3, [pc, #20] ;
2128: 220a    movs r2, #10
212a: 6819    ldr r1, [r3, #0]
212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
2132: 2064    movs r0, #100 ; 0x64
2134: f000 f8c2 bl 22bc <delay>
2138: bd10    pop {r4, pc}
213a: 46c0    nop ; (mov r8, r8)
213c: 200000bc .word 0x200000bc
2140: 200001a4 .word 0x200001a4

```

jum

Essentially, this code is doing a loop, running the following computation:

$$r0 = r1 + r3$$

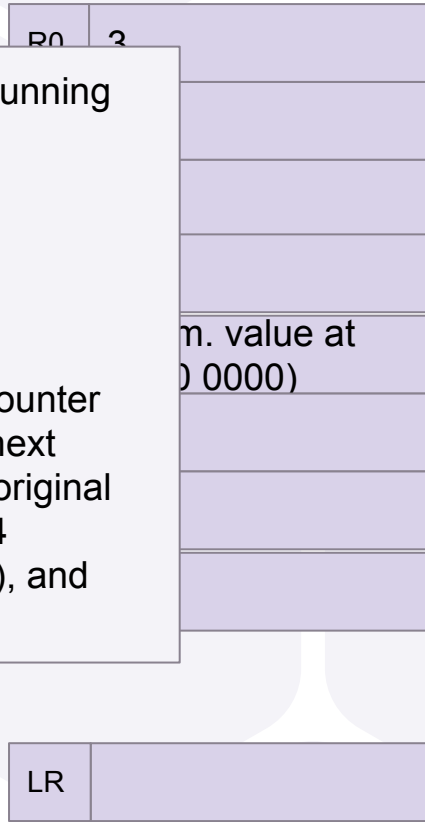
$$r2 = r2 + 1$$

$$r1 = r3$$

$$r3 = r0$$

And looping while $r2 < r4$ (so, $r2$ is a counter and $r0/r1/r3$ are used to compute the next fibonacci number). Going back to our original code, this suggests that the value at $r4$ (memory location 2000 0000) is 12 (N), and we'll run 12 iterations of this loop

previous stack



AFTER THE LOOP COMPLETES (ble.n 2116 at instruction 210a is executed)

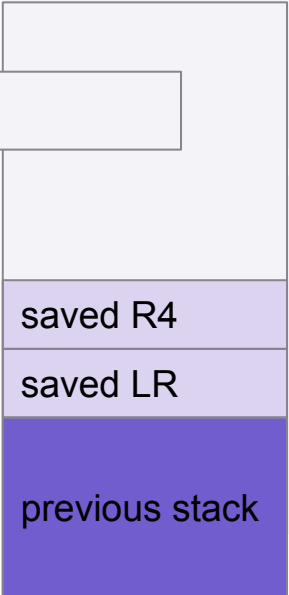
```

000020fc <setup>:
20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
20fe: b510    push {r4, lr}
2100: 681c    ldr r4, [r3, #0]
2102: 2301    movs r3, #1
2104: 2200    movs r2, #0
2106: 0019    movs r1, r3
2108: 4294    cmp r4, r2
210a: dd04    ble.n 2116 <setup+0x1a>
210c: 18c8    adds r0, r1, r3
210e: 3201    adds r2, #1
2110: 0019    movs r1, r3
2112: 0003    movs r3, r0
2114: e7f8    b.n 2108 <setup+0x1a>
2116: 4a02    ldr r2, [pc, #8] ; (2120 <setup+0x24>)
2118: 6013    str r3, [r2, #0]
211a: bd10    pop {r4, pc}
211c: 20000000 .word 0x20000000
2120: 200000bc .word 0x200000bc

00002124 <loop>:
2124: b510    push {r4, lr}
2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
2128: 220a    movs r2, #10
212a: 6819    ldr r1, [r3, #0]
212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
2132: 2064    movs r0, #100 ; 0x64
2134: f000 f8c2 bl 22bc <delay>
2138: bd10    pop {r4, pc}
213a: 46c0    nop ; (mov r8, r8)
213c: 200000bc .word 0x200000bc
2140: 200001a4 .word 0x200001a4
    
```



address 2116 + 8 = 2120



R0	(final value of R0)
R1	(final value of R1)
R2	2000 00bc
R3	(final value of R3)
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	

```

000020fc <setup>:
 20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
 20fe: b510    push {r4, lr}
 2100: 681c    ldr r4, [r3, #0]
 2102: 2301    movs r3, #1
 2104: 2200    movs r2, #0
 2106: 0019    movs r1, r3
 2108: 4294    cmp r4, r2
 210a: dd04    ble.n 2116 <setup+0x1a>
 210c: 18c8    adds r0, r1, r3
 210e: 3201    adds r2, #1
 2110: 0019    movs r1, r3
 2112: 0003    movs r3, r1
 2114: e7f8    b.n 2108 <setup+0x12>
 2116: 4a02    ldr r2, [pc, #4] ; (211a <setup+0x16>)
 2118: 6013    str r3, [r2, #0]
 211a: bd10    pop {r4, pc}
 211c: 20000000 .word 0x20000000
 2120: 200000bc .word 0x200000bc

```

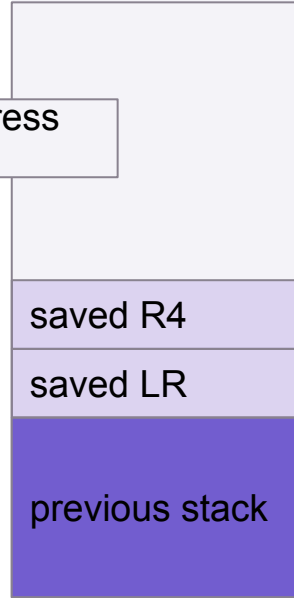


store final R3 value at address 2000 00bc

```

00002124 <loop>:
 2124: b510    push {r4, lr}
 2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
 2128: 220a    movs r2, #10
 212a: 6819    ldr r1, [r3, #0]
 212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
 212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
 2132: 2064    movs r0, #100 ; 0x64
 2134: f000 f8c2 bl 22bc <delay>
 2138: bd10    pop {r4, pc}
 213a: 46c0    nop ; (mov r8, r8)
 213c: 200000bc .word 0x200000bc
 2140: 200001a4 .word 0x200001a4

```



R0	(final value of R0)
R1	(final value of R1)
R2	2000 00bc
R3	(final value of R3)
R4	(mem. value at 2000 0000)
R5	
R6	
R7	
LR	

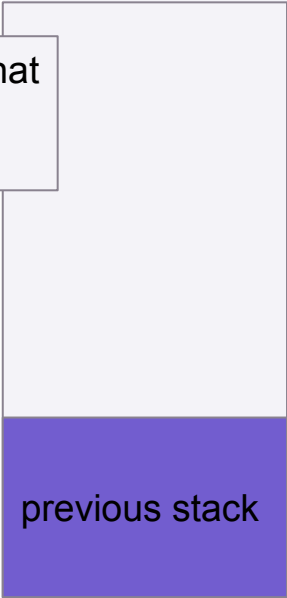
```

000020fc <setup>:
20fc: 4b07    ldr r3, [pc, #28] ; (211c <setup+0x20>)
20fe: b510    push {r4, lr}
2100: 681c    ldr r4, [r3, #0]
2102: 2301    movs r3, #1
2104: 2200    movs r2, #0
2106: 0019    movs r1, r3
2108: 4294    cmp r4, r2
210a: dd04    ble.n 2116 <setup+0x1a>
210c: 18c8    adds r0, r1, r3
210e: 3201    adds r1, r0, r2
2110: 0019    movs r2, r1
2112: 0003    movs r3, r2
2114: e7f8    b.n 2108
2116: 4a02    ldr r2, [r3, #0]
2118: 6013    str r3, [r2, #0]
211a: bd10    pop {r4, pc}
211c: 20000000 .word 0x20000000
2120: 200000bc .word 0x200000bc

00002124 <loop>:
2124: b510    push {r4, lr}
2126: 4b05    ldr r3, [pc, #20] ; (213c <loop+0x18>)
2128: 220a    movs r2, #10
212a: 6819    ldr r1, [r3, #0]
212c: 4804    ldr r0, [pc, #16] ; (2140 <loop+0x1c>)
212e: f002 f8d6 bl 42de <_ZN7arduino5Print7printlnEii>
2132: 2064    movs r0, #100 ; 0x64
2134: f000 f8c2 bl 22bc <delay>
2138: bd10    pop {r4, pc}
213a: 46c0    nop ; (mov r8, r8)
213c: 200000bc .word 0x200000bc
2140: 200001a4 .word 0x200001a4

```

popping into PC branches to that address (effectively returning from a subroutine)



R0	(final value of R0)
R1	(final value of R1)
R2	2000 00bc
R3	(final value of R3)
R4	saved R4
R5	
R6	
R7	
LR	



**Pipelining slides (not used
this semester)**

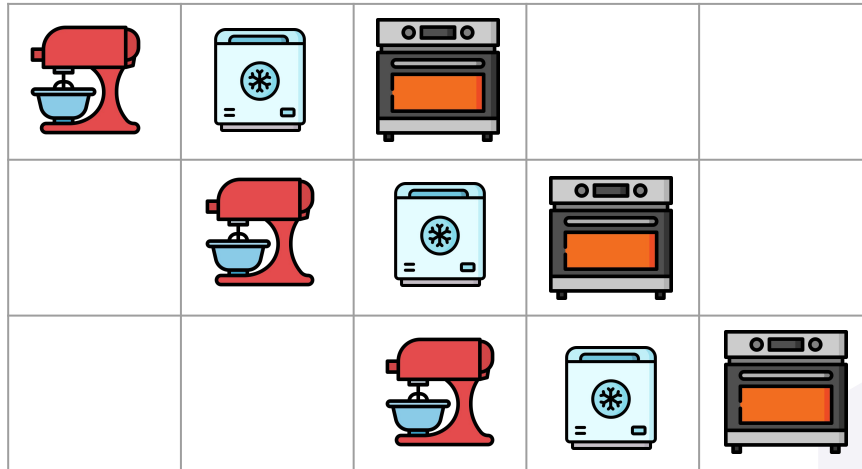
Sequential execution



Pipelining


















VS





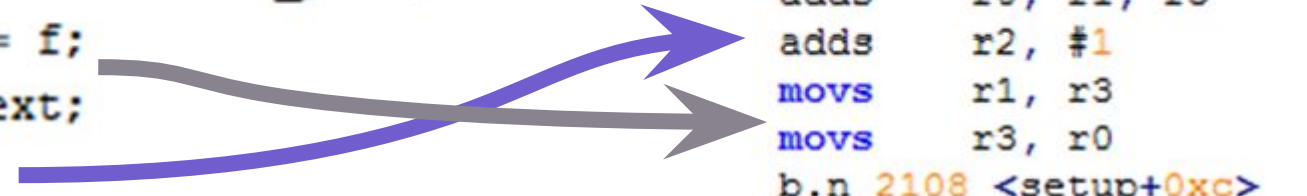
Pipeline hazards

Avoiding (some) hazards using compilation

```
while (i < N) {  
    int f_next = f + f_prev;  
    f_prev = f;  
    f = f_next;  
    i += 1;  
}
```

```
cmp r4, r2  
ble.n 2116 <setup+0x1a>  
adds r0, r1, r3  
adds r2, #1  
movs r1, r3  
movs r3, r0  
b.n 2108 <setup+0xc>
```





Can you summarize the tradeoff between deep and shallow pipelines and predict which kind MCUs are more likely to have?